

Fig. 1

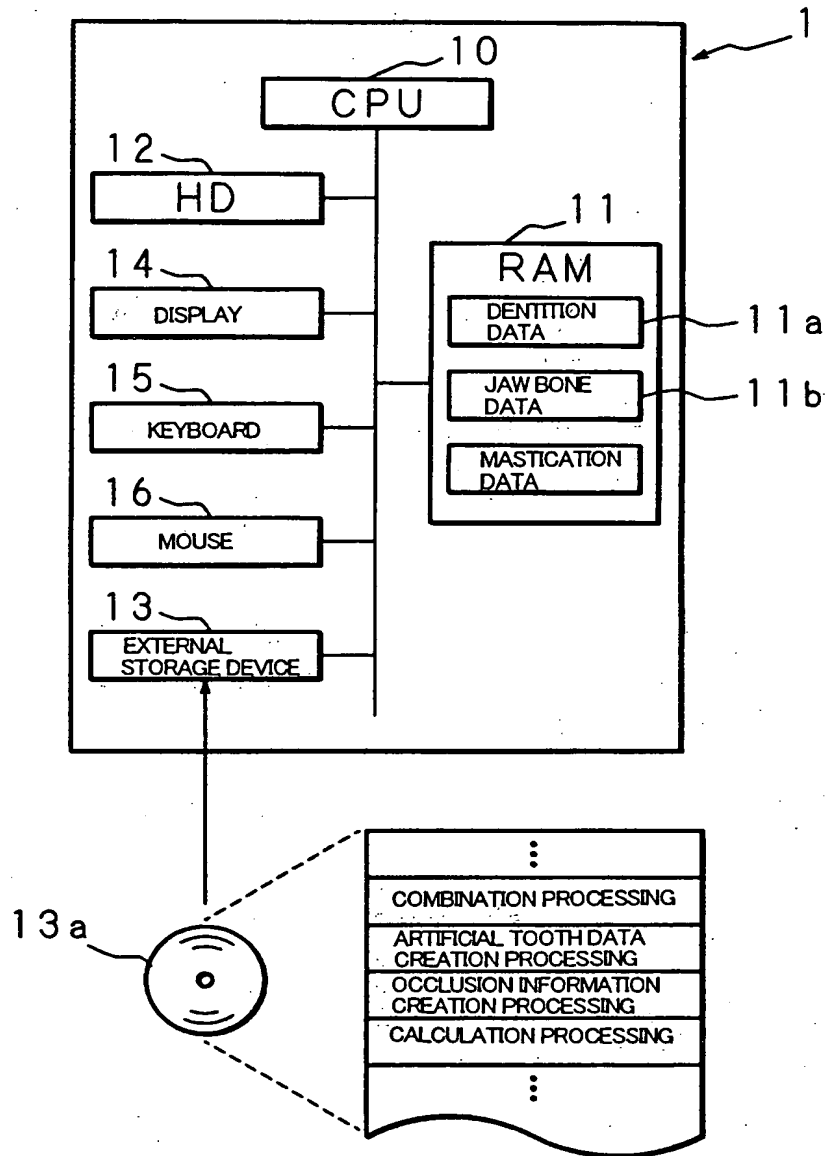
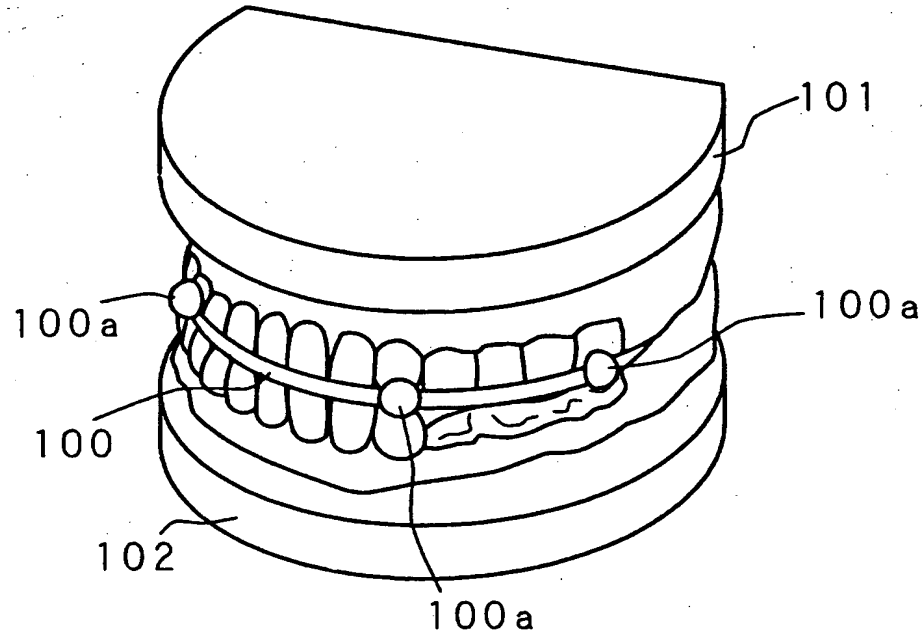
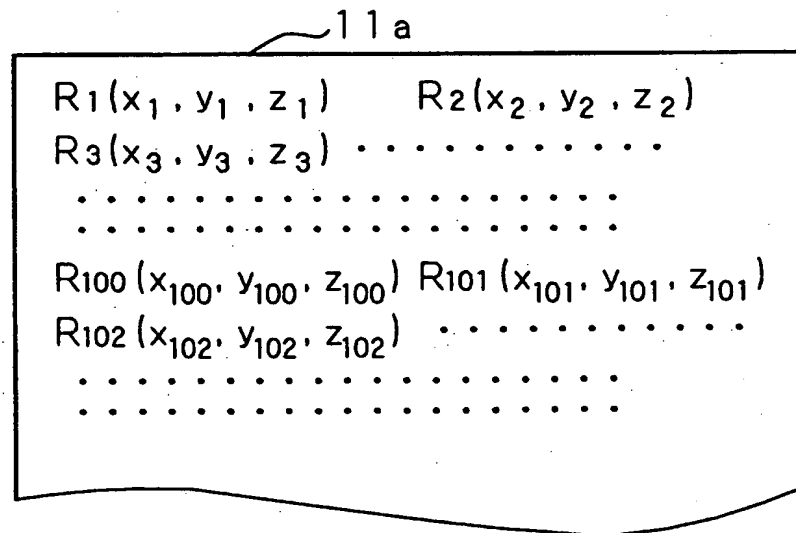


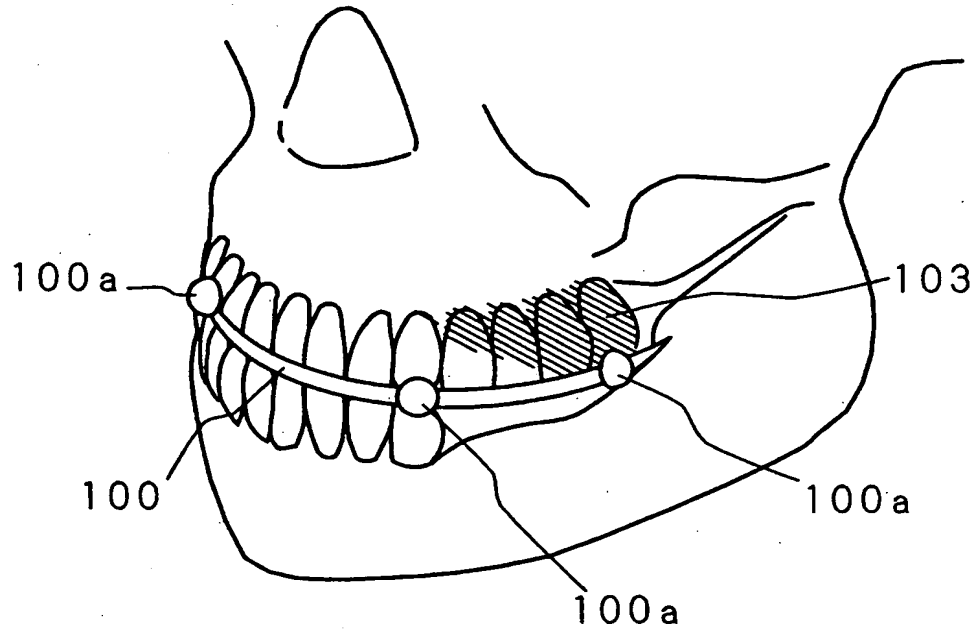
Fig. 2

A



B



*Fig. 3.***A****B**

11b

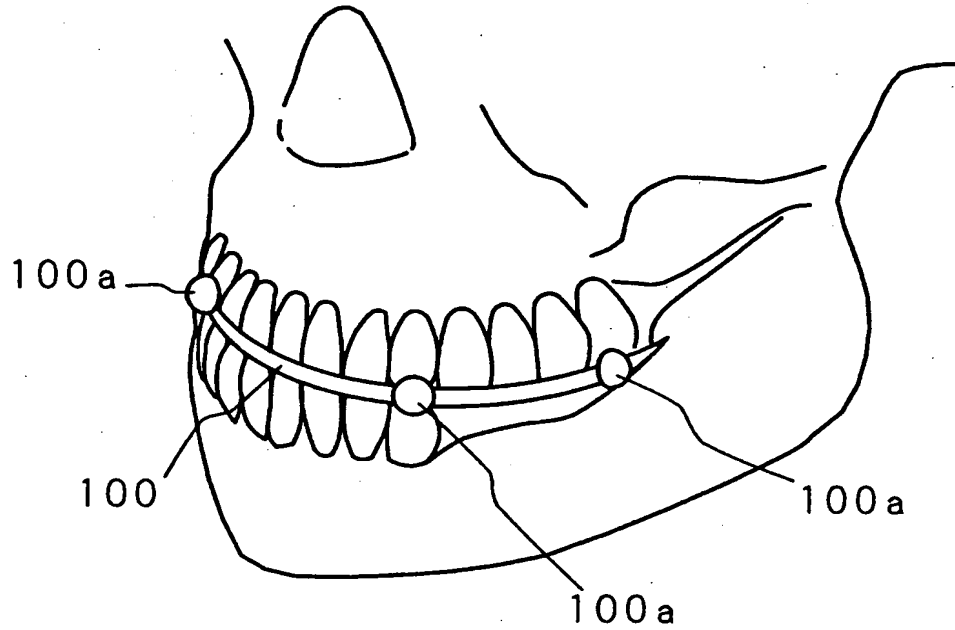
$$J_1(x_1, y_1, z_1, CT_1) \quad J_2(x_2, y_2, z_2, CT_2)$$

$$J_3(x_3, y_3, z_3, CT_3) \quad \dots\dots\dots$$

$$\dots\dots\dots$$

$$J_{200}(x_{200}, y_{200}, z_{200}, CT_{200}) \quad J_{201}(x_{201}, y_{201}, z_{201}, CT_{201})$$

$$\dots\dots\dots$$

*Fig. 4**A**B*

$$\begin{array}{l}
 J_1(x_1, y_1, z_1, CT_1) \quad J_2(x_2, y_2, z_2, CT_2) \\
 J_3(x_3, y_3, z_3, CT_3) \quad \dots\dots\dots \\
 \dots\dots\dots \\
 R_1(x_1, y_1, z_1) \quad R_2(x_2, y_2, z_2) \\
 R_3(x_3, y_3, z_3) \quad \dots\dots\dots \\
 \dots\dots\dots
 \end{array}$$

Fig. 5

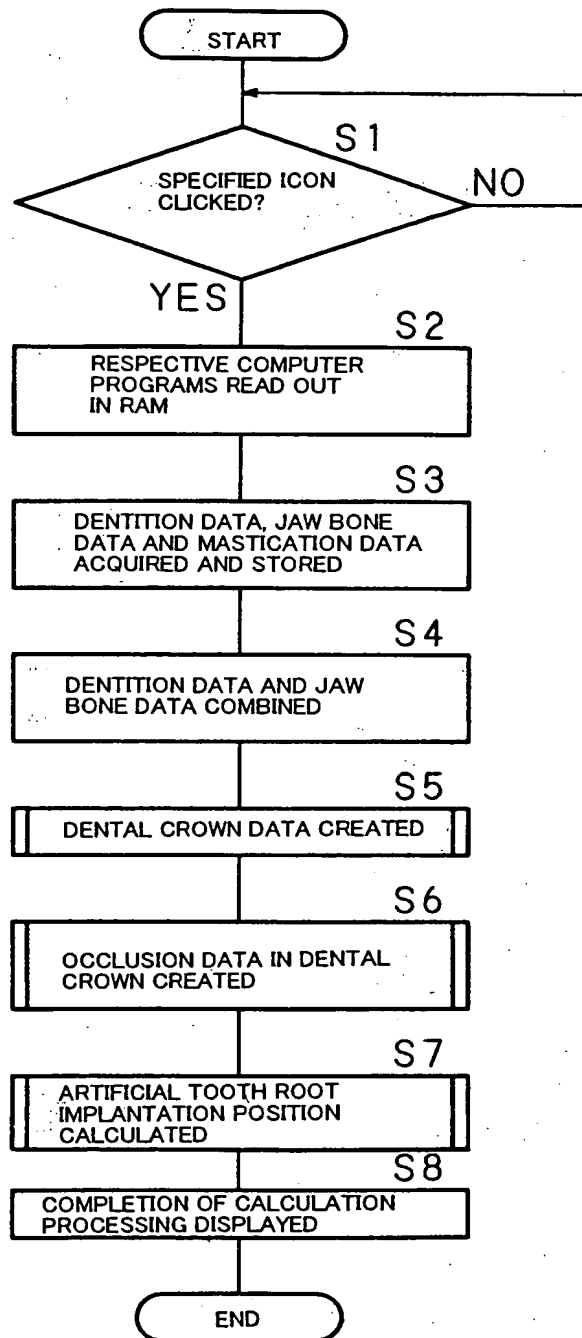


Fig. 6

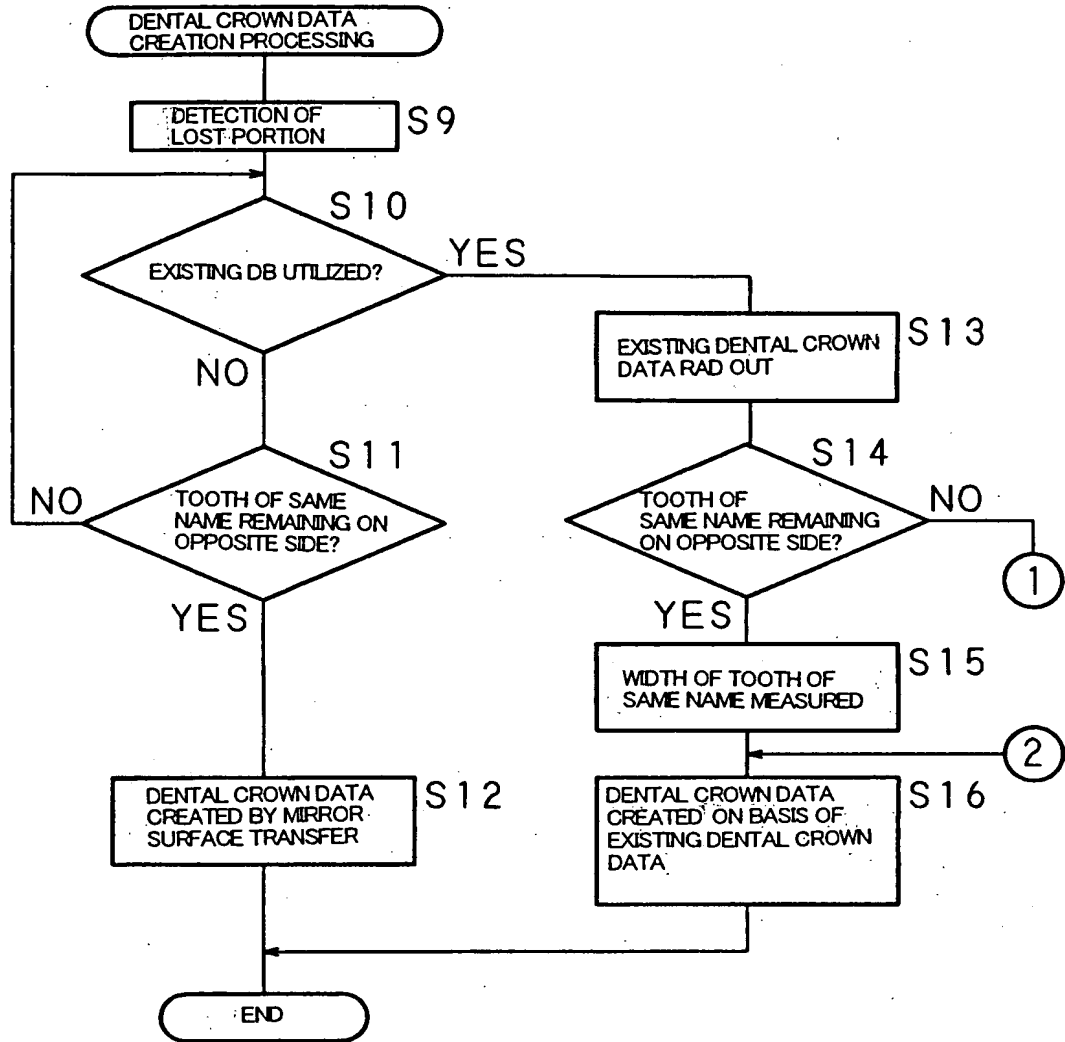


Fig. 7

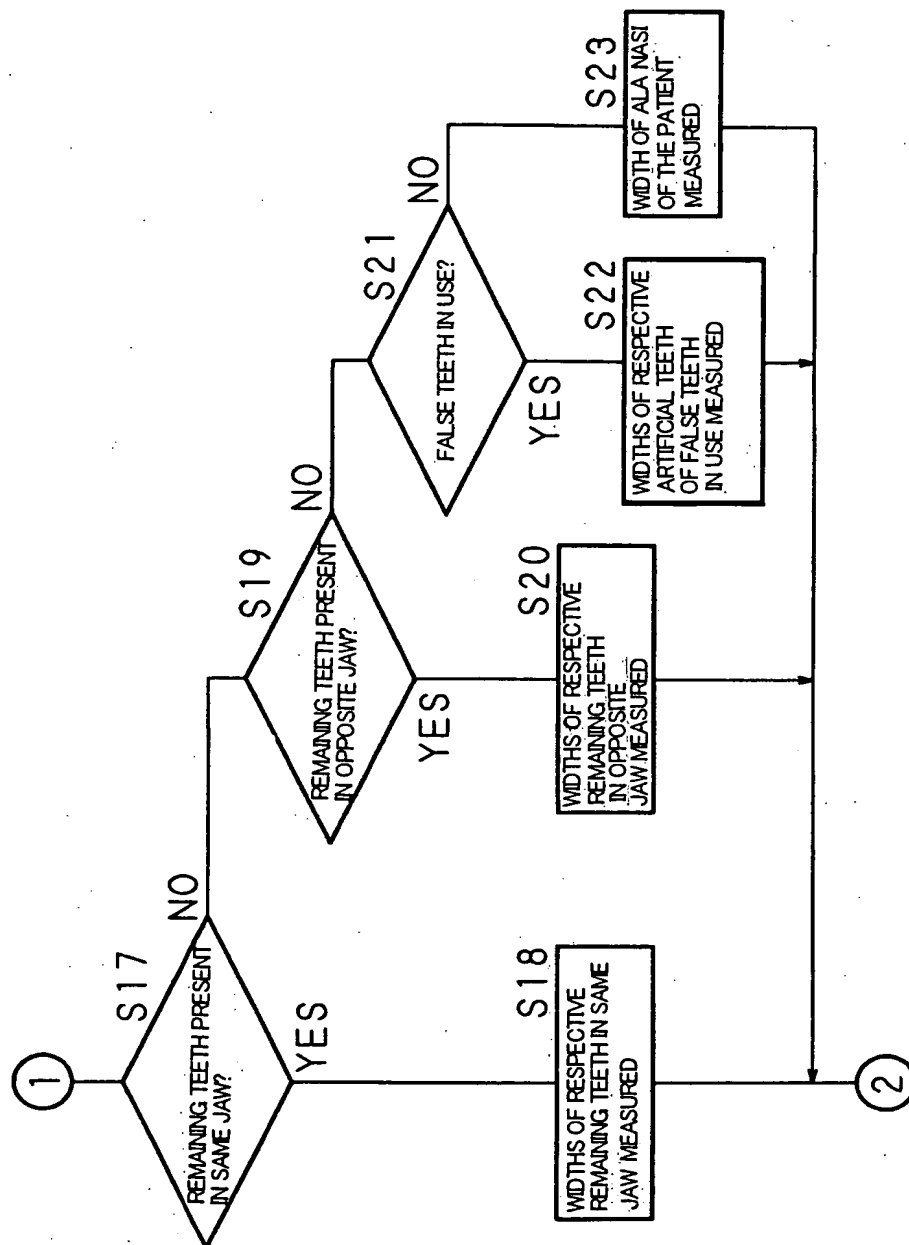


Fig. 8

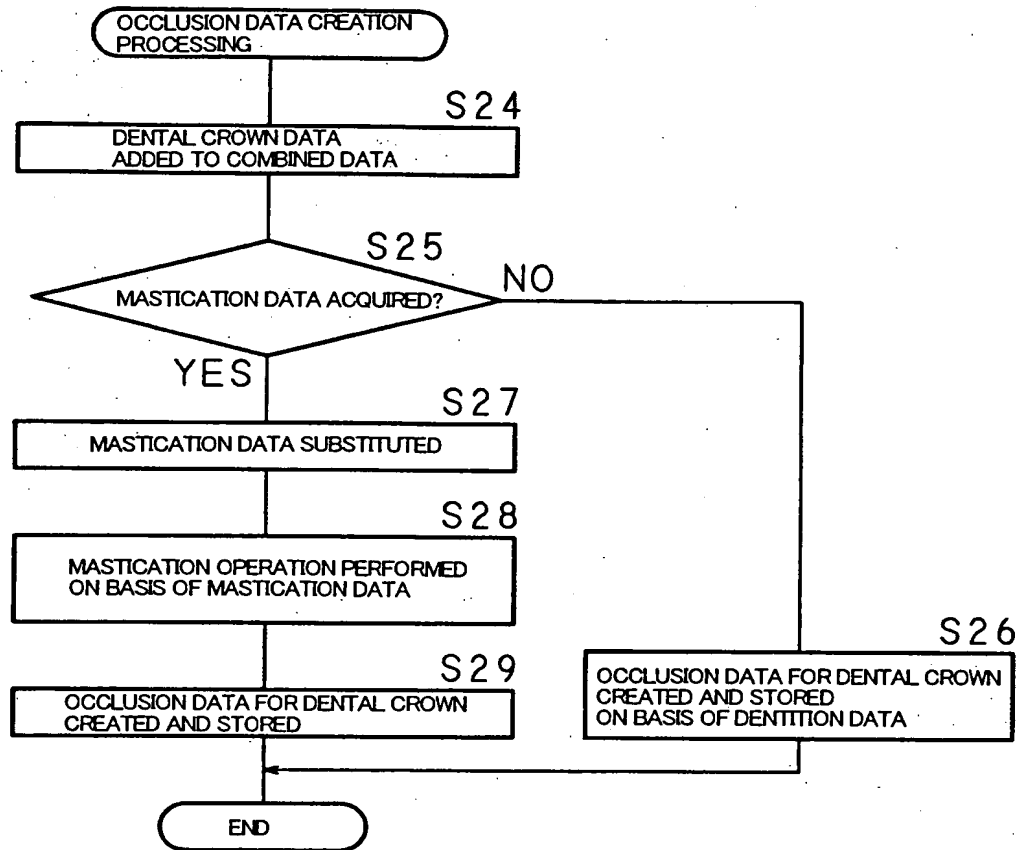


Fig. 9

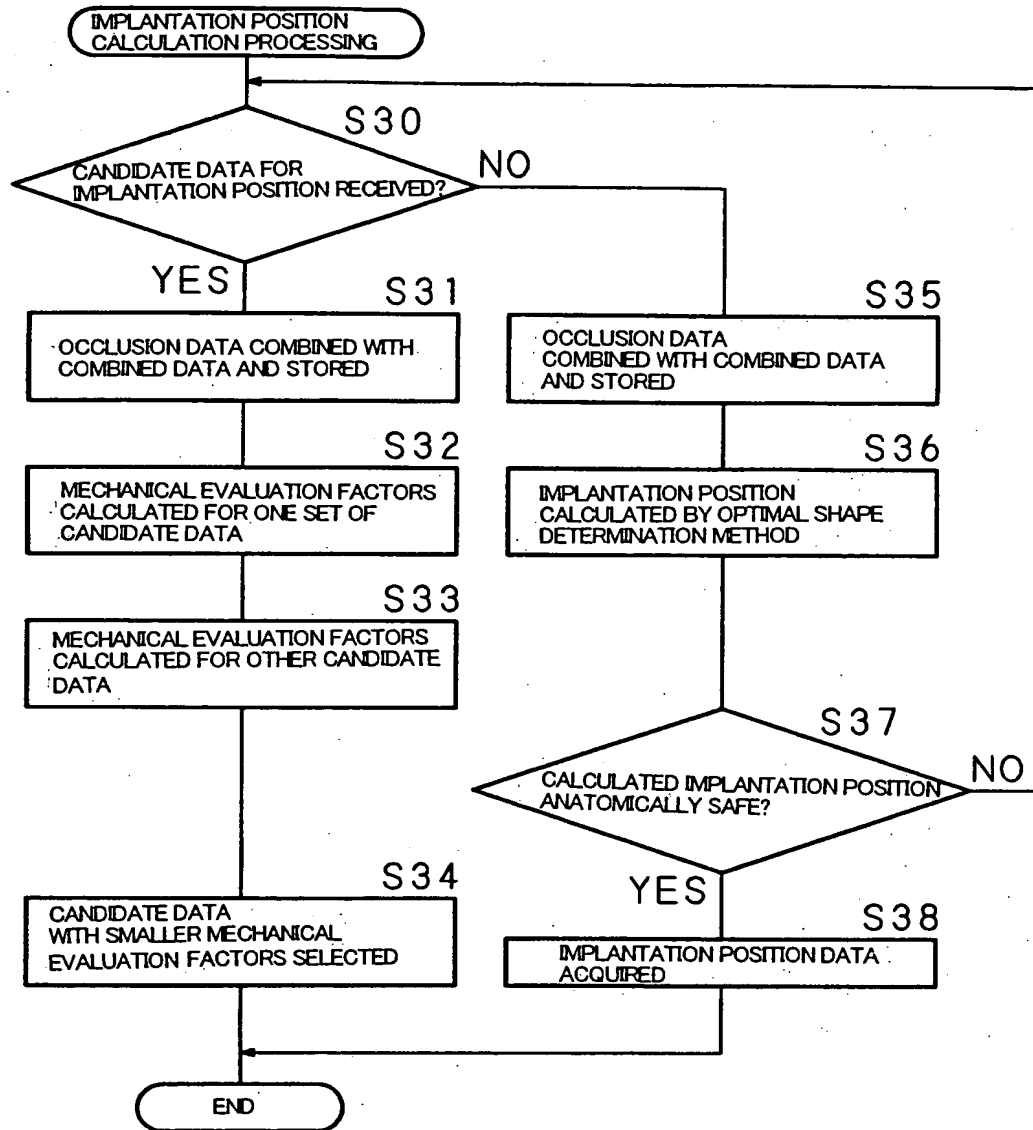


Fig. 10

2

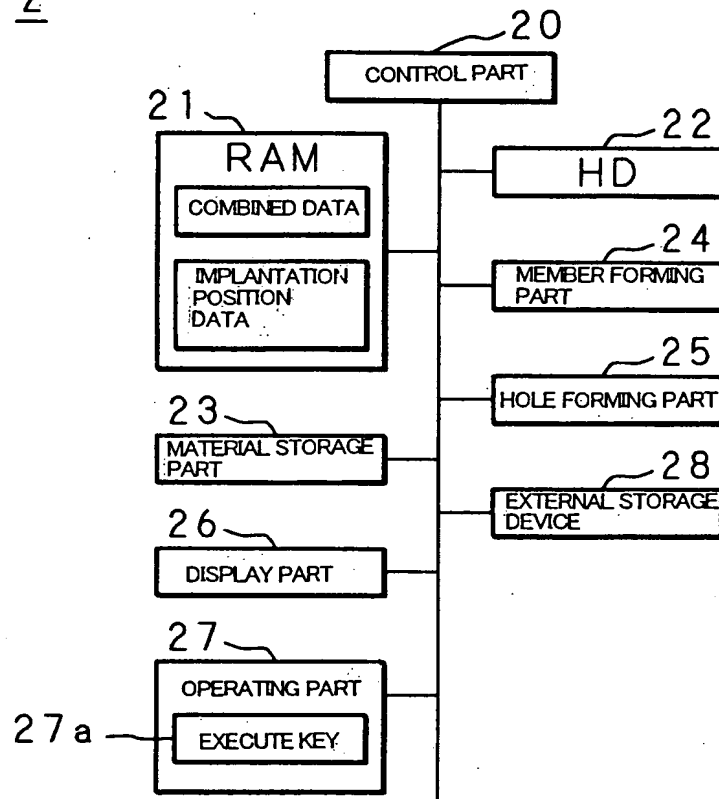


Fig. 11

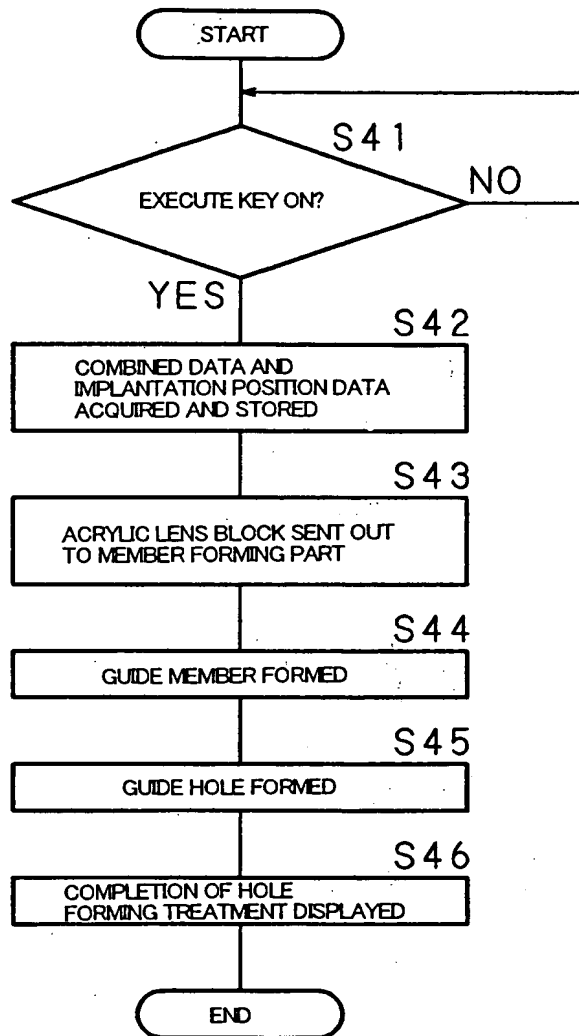


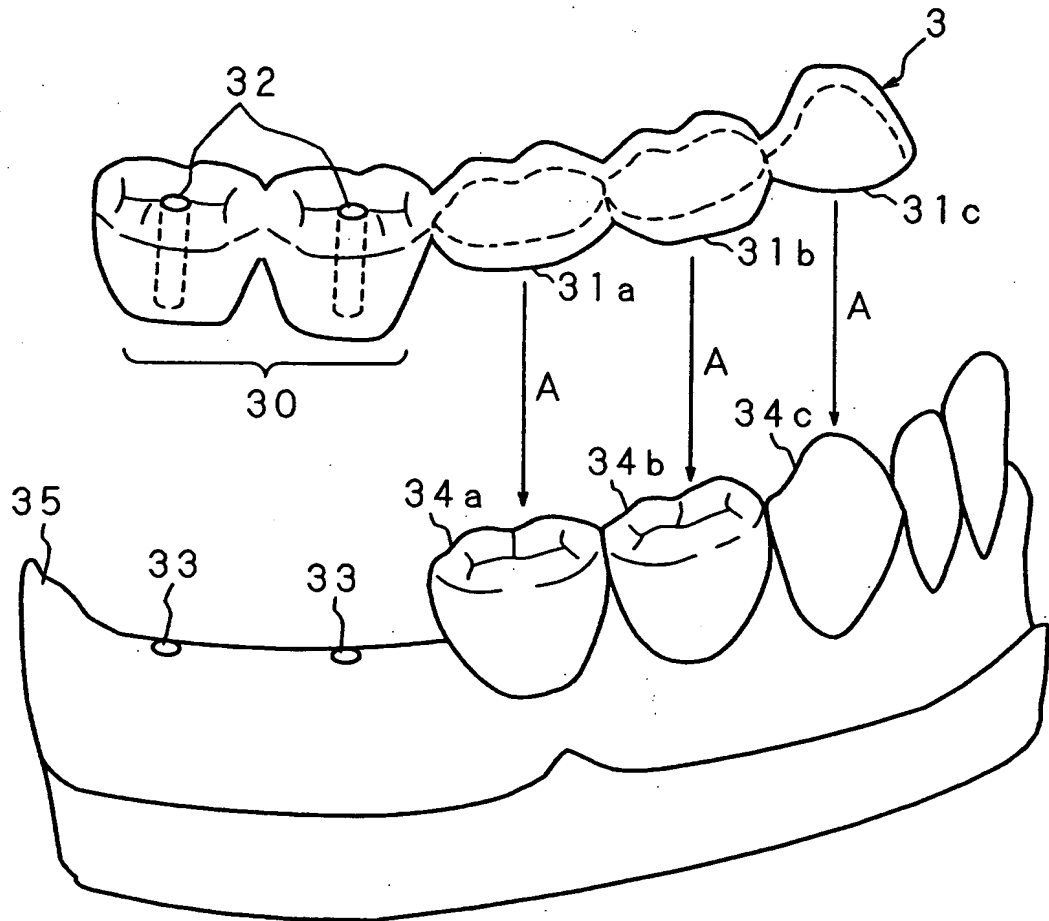
Fig. 12

Fig. 13

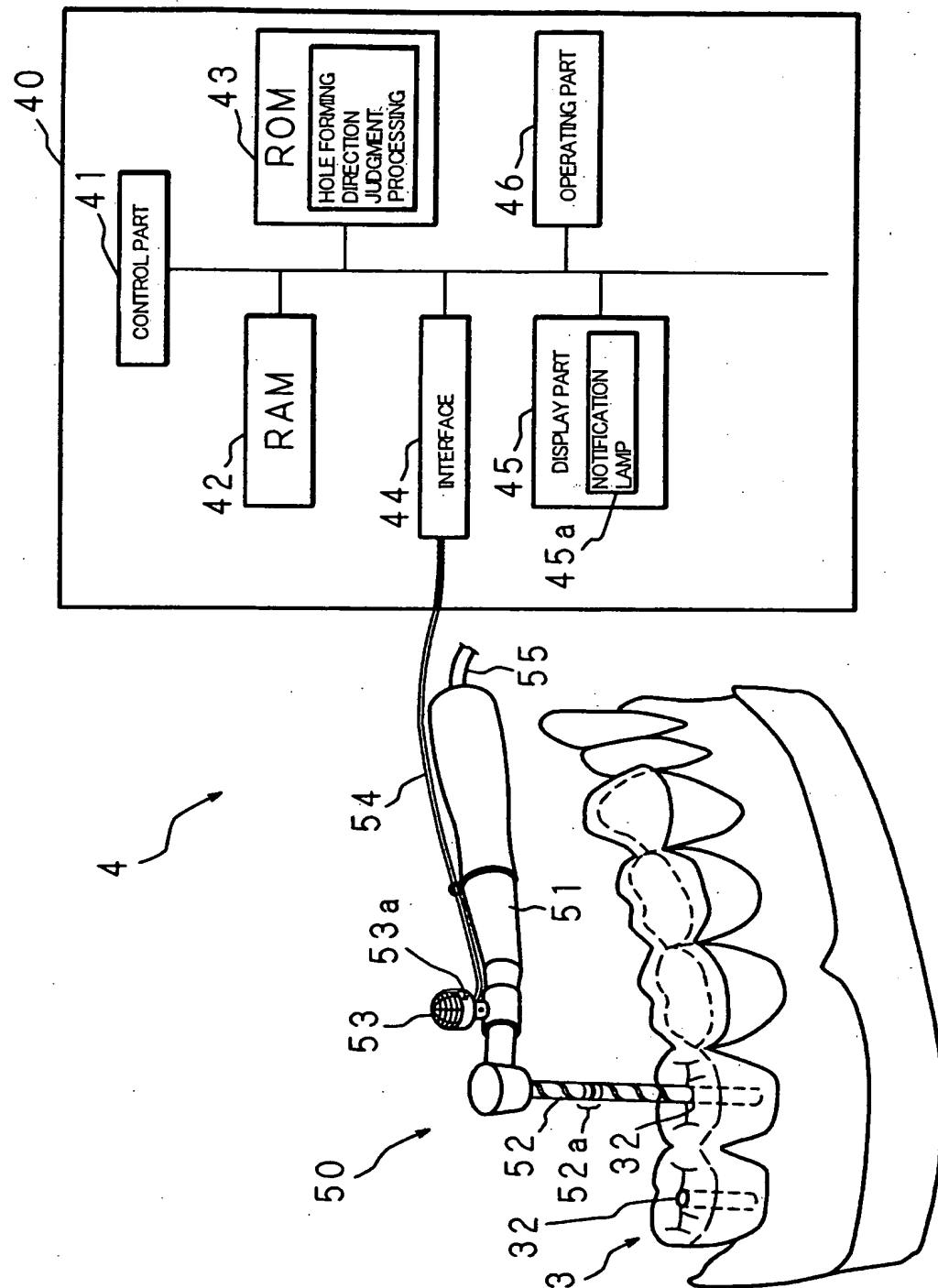


Fig. 14

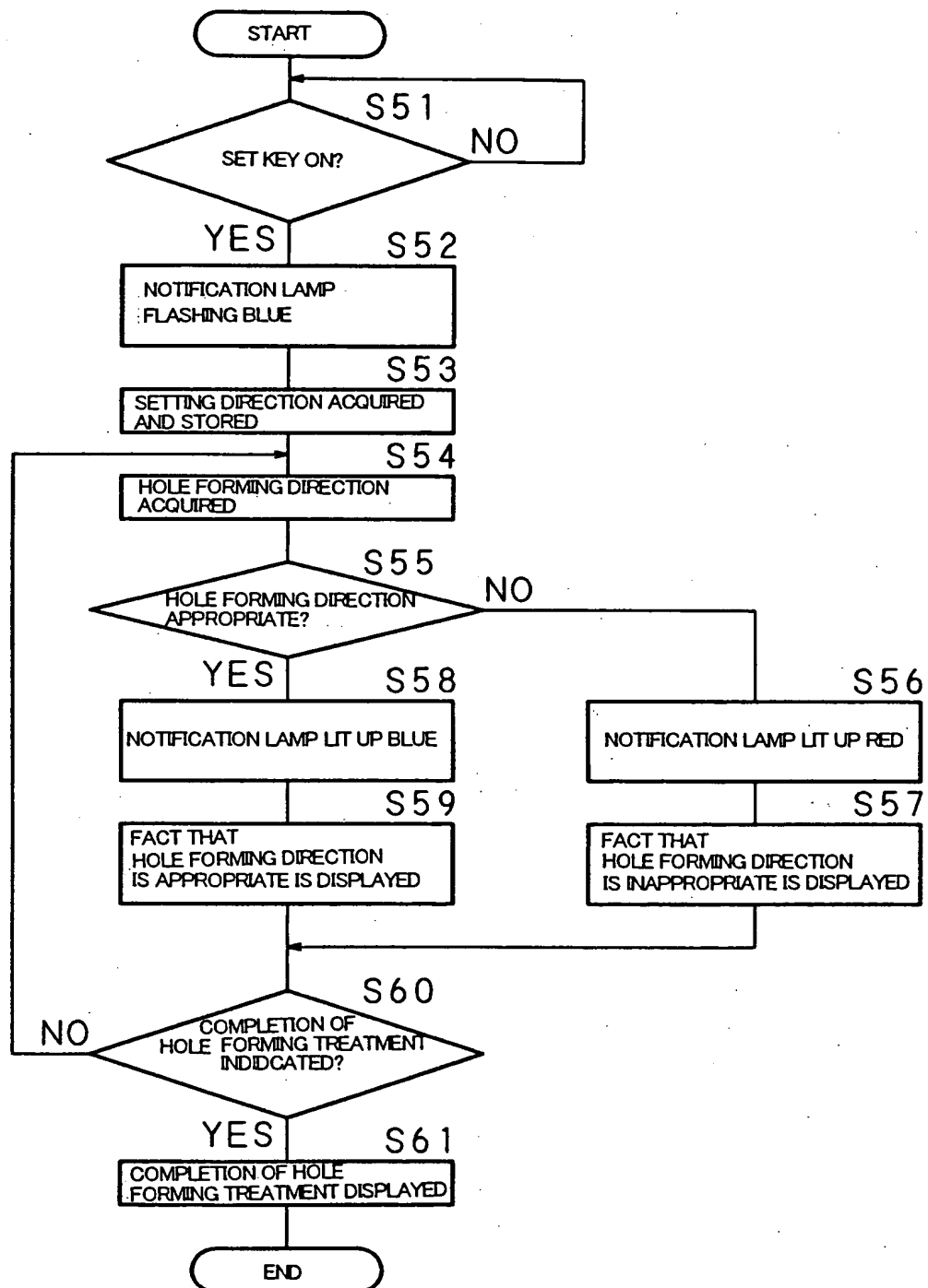


Fig. 15

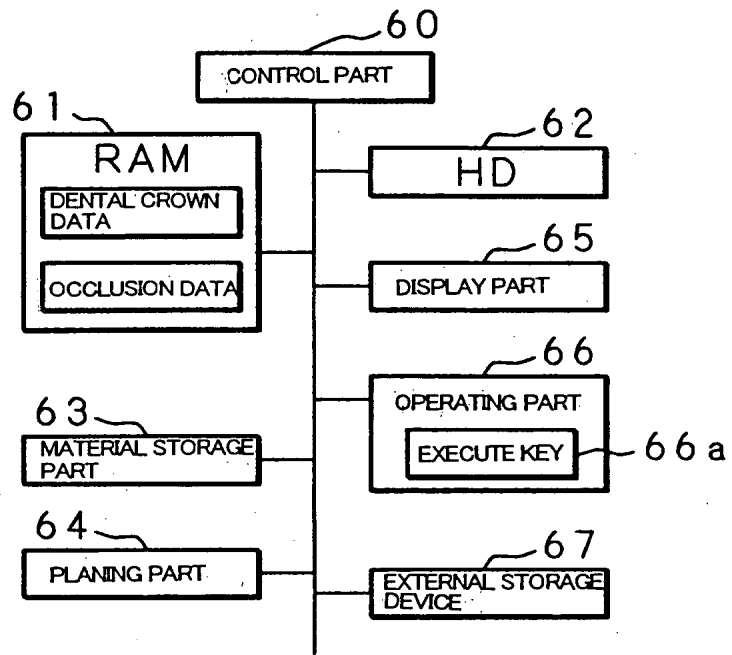
6

Fig. 16

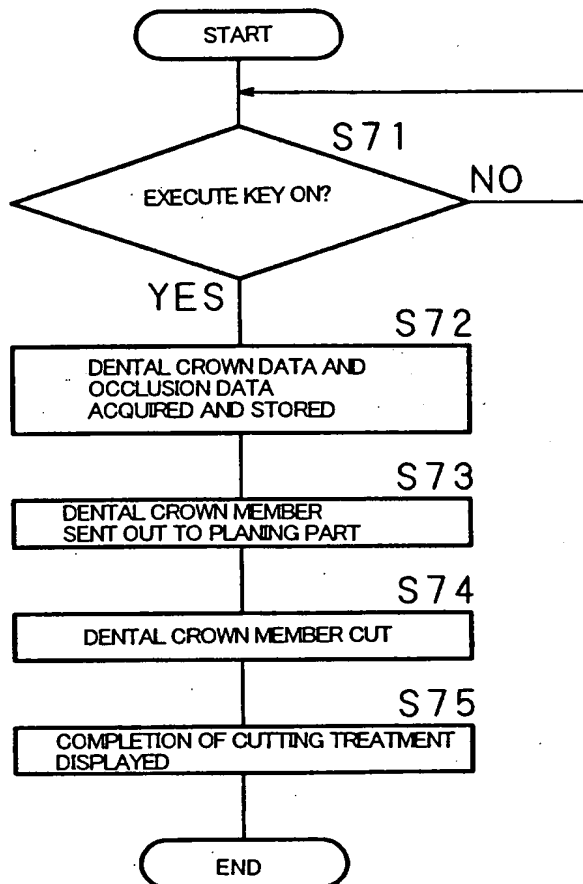


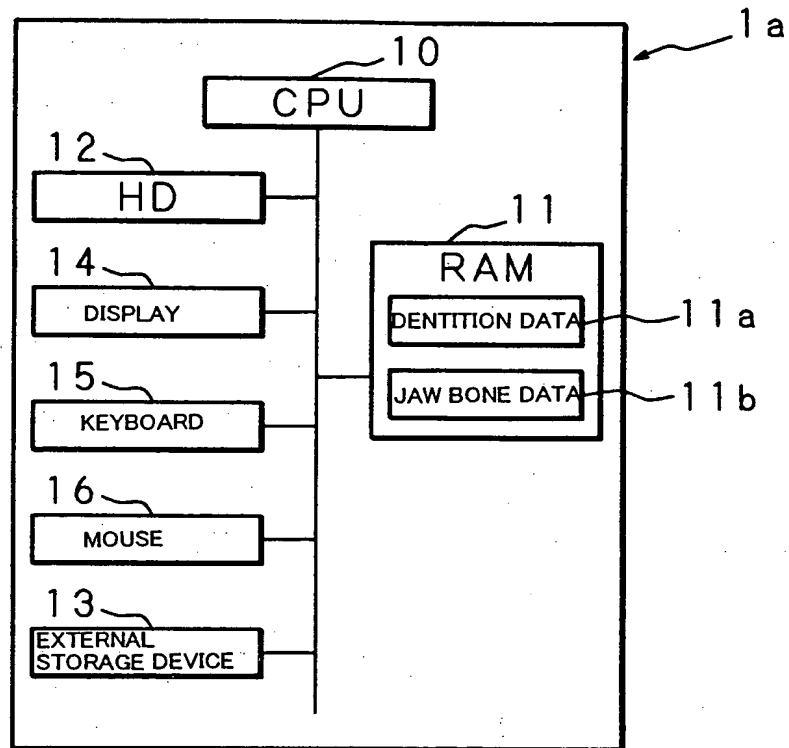
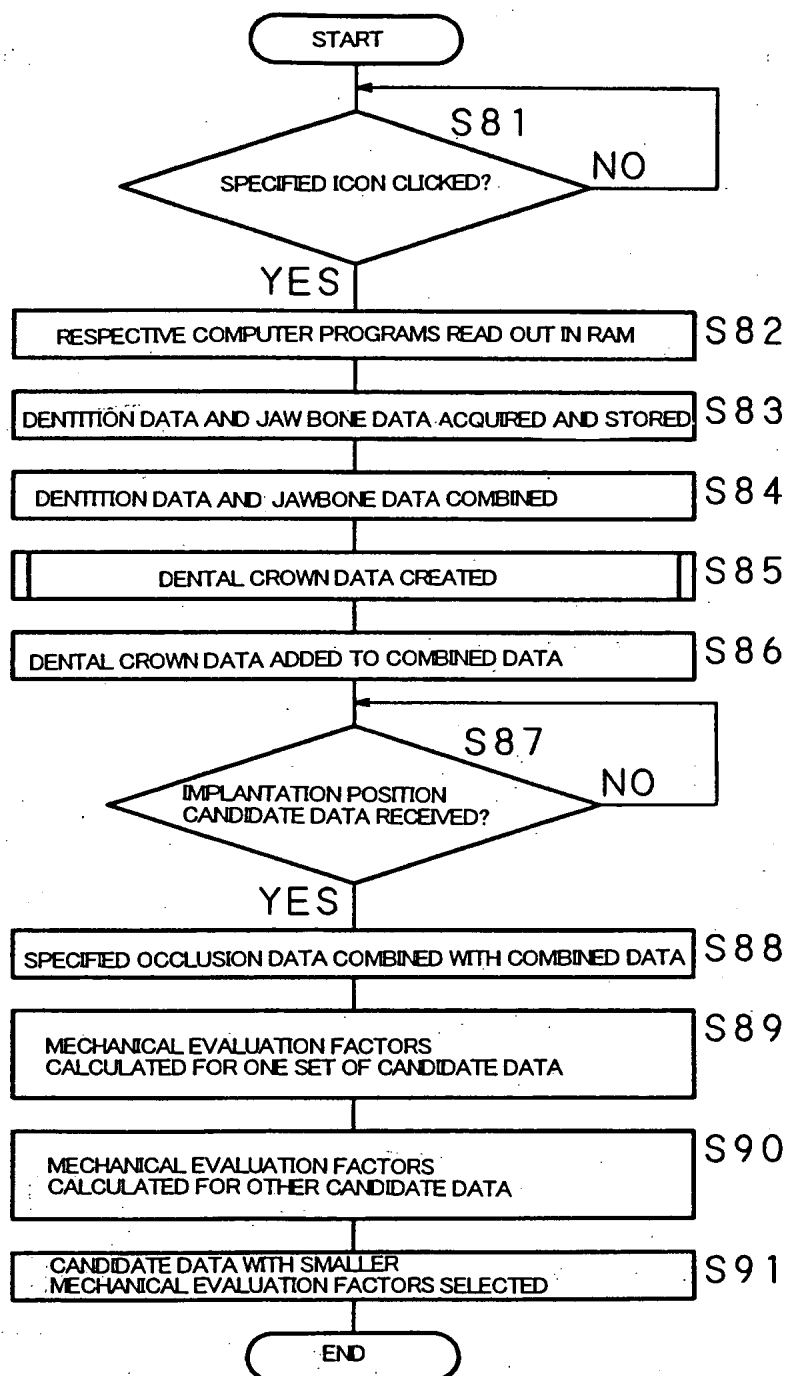
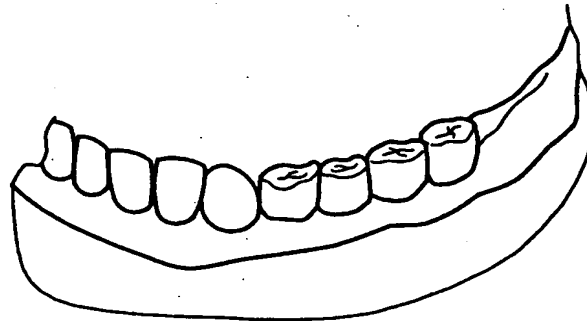
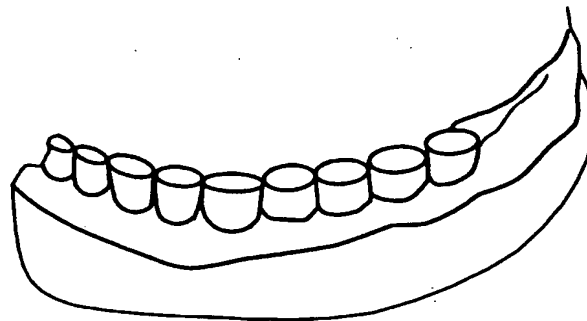
Fig. 17

Fig. 18



*Fig. 19**A**B**C*